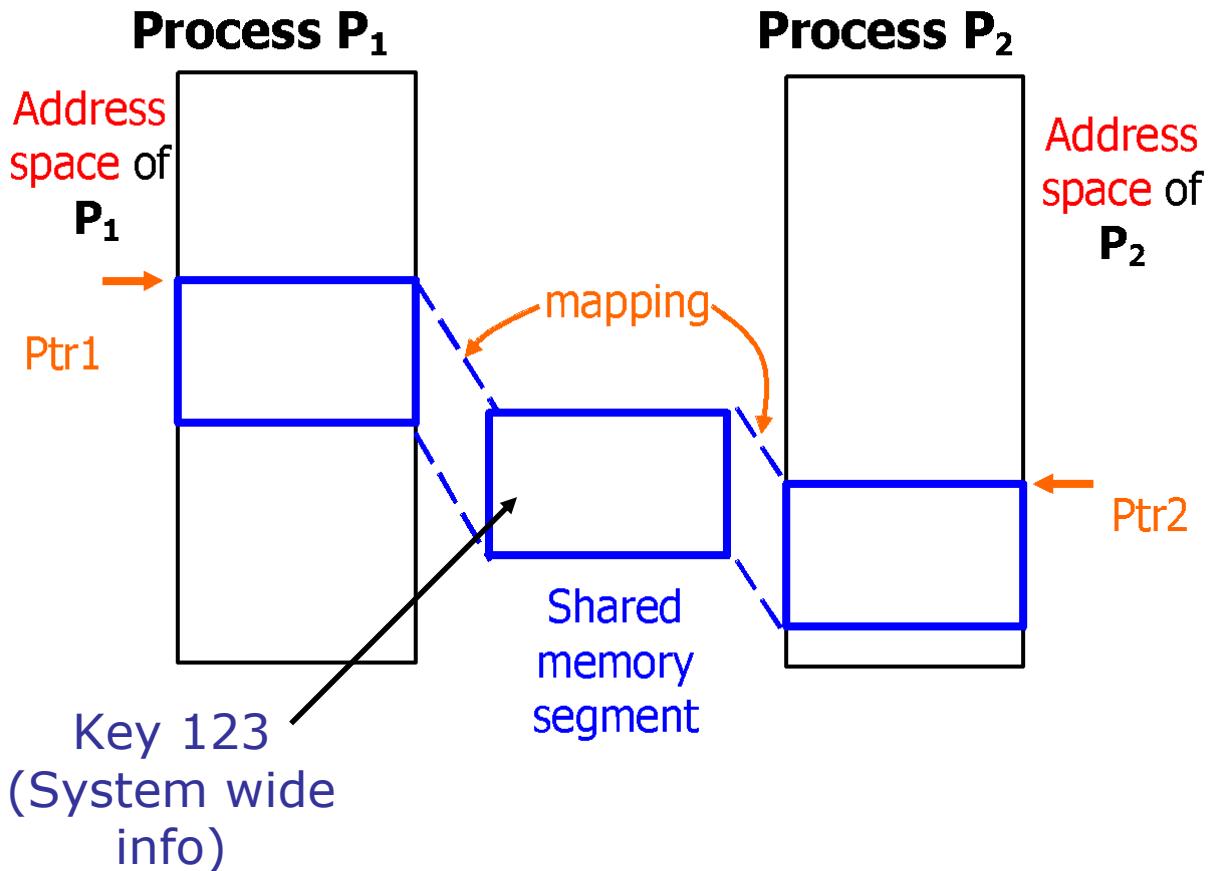


Interprocess Communication IPC Shared Memory

Shared Memory Concept



How to Create Shared Memory

- One of the processes **creates** a shared segment. Other processes **get ID** of the created segment
- Each process, using the **same key**, **attaches** to itself the created shared segment
- Now each process may **write** and **read** data into the shared segment
- Each process **detaches** the segment (**after finishing**)

System Calls for Shared Memory

```
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/shm.h>
```

1. Creating a shared segment or getting its ID

```
int id = shmget ( key, size, flag );
```

Numeric key of type int → **key**
Size of the segment in bytes, int → **size**
IPC_CREAT | 0666 → **flag**

int → **id**

To create new segment with rw-rw-rw- Or 0 to get an ID of existing segment → **IPC_CREAT | 0666**

Shared memory is allocated but NOT mapped ... → **flag**

System Calls for Shared Memory

2. Attaching (mapping) the existing memory segment (getting its pointer).

```
From shmget()           Address to map at (typically  
                           0, let system choose)  
  
ptr = shmat( id, addr, flag );  
  
Starting  
address of  
shared  
segment      Typically 0, or  
                           SHM_RDONLY  
                           Now shared  
                           memory is  
                           mapped
```

```
Typedef struct shmid_ds{  
    struct ipc_perm shm_perm; /* operation permission  
                                structure */  
    size_t shm_segsz;          /* size of segment in  
                                bytes */  
    pid_t shm_lpid;           /* process ID of last operation  
                                */  
    pid_t shm_cpid;           /* process ID of creator */  
    shmat_t shm_nattch;       /* number of current attaches  
                                */  
    time_t shm_atime;         /* time of last shmat */  
    time_t shm_dtime;         /* time of last shmdt */  
    time_t shm_ctime;         /* time of last shctl */  
} shmid_ds
```

Example

```
/* Header file line.h */
struct info {
    char c;
    int length;
};

#define key ((key_t)(key = 1243));
#define MSIZ sizeof(struct info)
```

Example

Process A

```
#include <stdio.h>
#include <stdlib.h>
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/shm.h>
#include <unistd.h>
#include "line.h"

main(void)
{
    int i, id ;
    struct info *ctrl;

    if ( (id = shmget( key,MSIZ,IPC_CREAT | 0666 ) ) <
0 )
    {
        printf("error 1\n");
        exit(1) ;
    }

    if ( (ctrl = (struct info *) shmat( id, 0, 0)) <= (struct
info *) (0) )
    {
        printf("error 2\n");
        exit(1) ;
    }
}
```

Process B

```
#include <stdio.h>
#include <stdlib.h>
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/shm.h>
#include "line.h"

main(int argc, char *argv[])
{
    int id ;
    struct info *ctrl;

    if (argc < 3)
    {
        exit(3);
    }

    if ( (id = shmget( key,MSIZ, 0 )) < 0 )
    {
        exit(1) ;
    }

    ctrl = (struct info *) shmat( id, 0, 0);
    if ( ctrl <= (struct info *) (0) )
    {
        exit(1) ;
    }
}
```

Example

Process A

```
ctrl->c = 'a';
ctrl->length = 10;

// print line every 4 seconds
for (i = 0 ; i <ctrl->length ; i++ )
{
    putchar (ctrl->c);
    putchar ('\n');
    sleep(4);
}

//now detach the pointer from the shared memory
shmdt(ctrl);
//let us delete the shared memory
shmctl(id,IPC_RMID,NULL);

//job done
}
```

Process B

```
ctrl->c = argv[1][0] ;
ctrl->length = atoi(argv[2]);

//detach the pointer from the shared memory
shmdt(ctrl);
exit(0);
```

Example 2

Header

```
struct info {  
    char c;  
    int length;  
    char flag;  
};  
key_t key = 1243 ;  
#define MSIZ sizeof(struct info)
```

Example 2

Process C

```
#include <stdio.h>
#include <stdlib.h>
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/shm.h>
#include "header.h"

main(void)
{
    int i, id ;
    struct info *ctrl;

    if ( (id = shmget( key,MSIZ,IPC_CREAT | 0666 ) ) <
0 )
    {
        printf("error 1\n");
        exit(1) ;
    }

    if ( (ctrl = (struct info *) shmat( id, 0, 0)) <= (struct
info *) (0) )
    {
        printf("error 2\n");
        exit(1) ;
    }

    ctrl->c = 'a';
    ctrl->length = 10;
    ctrl->flag = 0;
```

Process D

```
#include <stdio.h>
#include <stdlib.h>
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/shm.h>
#include "header.h"

main(int argc, char *argv[])
{
    int id ;
    struct info *ctrl;
    if (argc < 3)
    {
        exit(3);
    }

    if ( (id = shmget( key,MSIZ, 0 )) < 0 )
    {
        exit(1) ;
    }

    ctrl = (struct info *) shmat( id, 0, 0);
    if ( ctrl <= (struct info *) (0) )
    {
        exit(1) ;
    }

    // wait until Process C is ready to receive from process D
    while(ctrl->flag==0);
```

Example 2

Process C

```
for (i = 0 ; i <ctrl->length ; i++)
{
    putchar (ctrl->c);
    putchar (' ');
}
putchar('\n');
fflush(stdout);
ctrl->flag = 2;
while(ctrl->flag!=1);

// print the character ctrl->c for ctrl->length times in a single line
for (i = 0 ; i <ctrl->length ; i++)
{
    putchar (ctrl->c);
    putchar (' ');
}
putchar ('\n');
// flushing stdout just in case
fflush(stdout);

//now detach the pointer from the shared memory
shmdt(ctrl);
//let us delete the shared memory
shmctl(id,IPC_RMID,NULL);

//job done
}
```

Process D

```
/* copy command line data to shared memory */
ctrl->c = argv[1][0];
ctrl->length = atoi(argv[2]);
ctrl->flag = 1;

//detach the pointer from the shared memory
// .. we do not need to delete here, can be done in either of the process
shmdt(ctrl);
exit(0);
}
```

Shared Memory Features

- **Efficiency** (no intermediate copying of data as in pipes)
- **Random access** (a sequential byte stream in pipes)
- **Many-to-many mechanism** of IPC: many processes may attach the same segment (**pipes provide one-to-one** mechanism of IPC)
- **No synchronization** is provided (**pipes provide** synchronization)
- Limitations on the number of shared memory segments:
 - Some of these can be changed by a system administrator, by configuring a new kernel. These limits are: maximum and minimum size in bytes; max no. of shared memory segments, system wide and per process.